

#### Panel Models

By Chahir Zaki

Training on Applied Micro-Econometrics and Public Policy Evaluation

**Economic Research Forum** 

# Outline

- Introduction
- Fixed Effects
- Random Effects
- Choosing Between Them
- Stata Application

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#### Introduction

Balanced panel data: we observe the same number of periods for each individuals so that the number of observation= N.T

- When N = 1 and T > 1: Time series analysis
- When T = 1 and N > 1: Cross-section analysis
- When T > 1 and N > 1 and T < N: Panel analysis
- When T > 1 and N > 1 and T > N: TSCS

# The Basic Data Structure



#### Panel Data Models

- These types of models attempt to account for correlation between observable variables and unobservable variables (Arellano 2003).
- Such heterogeneity can be caused by multiple factors, such as simultaneity (when the independent variables are correlated with the dependent variable), measurement error (which results in the independent variables being correlated with the error term, and the unobserved heterogeneity, which results in both the independent variables being correlated with the error term and bias in the coefficients (Arellano 2003).

#### Panel Data Models

- Panel data regression models are based on panel data, which are observations on the same cross-sectional, or individual, units over several time periods.
- A balanced panel has the same number of time observations for each cross-sectional unit.
- Panel data have several advantages over purely cross-sectional or purely time series data. These include:
  - Increase in the sample size
  - Study of dynamic changes in cross-sectional units over time
  - Study of more complicated behavioral models, including study of timeinvariant variables

#### Possible Combinations of Slopes and Intercepts



Separate regression for each individual

Varying slopes Varying intercepts





The assumptions required for this model are unlikely to hold

Varying slopes Constant intercept

Constant slopes Constant intercept

## Unobserved Heterogeniety

- Omitted variables bias
- Many individual characteristics are not observed
  - e.g. enthusiasm, willingness to take risks
- These vary across individuals described as unobserved heterogeneity
- If these influence the variable of interest, and are correlated with observed variates, then the estimated effects of these variables will be biased

### Problems of Panel

- Some specific problems with panel data model need to be kept in mind:
  - The most serious problem is the problem of attrition, whereby for one reason or another, members of the panel drop out over time so that in the subsequent surveys (i.e., cross-sections) fewer original subjects remain in the panel.
  - Also, over time subjects may refuse or be unwilling to answer some questions.

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#### General Form

$$y_{it} = \alpha + X_{it}\beta + \mu_i + \lambda_t + v_{it}$$
$$u_{it} = \mu_i + \lambda_t + v_{it}$$
$$i = 1, \dots, N, t = 1, \dots, T$$

where

- $y_{it}$  is the dependent variable,
- $\alpha$  is the intercept,
- $X_{it}$  is the matrix of explanatory variables with coefficients  $\beta$ ,
- $u_{it}$  is the disturbance term,
- $\mu_i$  represents unobserved cross-sectional (individual) effects for N cross sections,
- $\lambda_t$  represents unobserved time-series effects for T time periods, and
- $v_{it}$  represents random or idiosyncratic disturbances.

## Pooled OLS and Its limitations

• An OLS estimation of panel data would look as follows  $y_t = \alpha \pm \beta X_t \pm \beta T_t \pm \gamma T_t t \pm \delta t \pm \delta t$ 

 $y_{it} = \alpha + \beta X_{it} + \theta T_i + \gamma T_i t + \delta t + \varepsilon_{it}$ 

- To get consistent estimates of the parameters  $\alpha$ ,  $\beta$ , $\theta$  and  $\gamma$  using this model, the following conditions must be satisfied:
- 1. Linearity with respect to independent variables  $X_{it} T_{it}$  and  $e_{it}$
- 2. Exogeneity. Expected value of disturbances  $\varepsilon_{it}$  is zero and the are not correlated to any regressors (i.e. omitted variables are not correlated with included variables)
- 3. Disturbances  $e_{it}$  are independent and identically distributed, have the same variance (homoscedasticity) and not related to each other (non-auto-correlated)
- 4. Non-stochastic independent variables
- No exact multi-collinearity among independent variables (full-rank)
   If there are time-invariant individual effects u<sub>i</sub> ≠ 0, this might violate assumptions 2 and 3.

# Fixed and Random Effects Models

- Now we will allow for time-invariant individual effects.
- The model can be re-written in two ways
- Fixed effects:  $y_{it} = (\alpha + u_i) + \beta X_{it} + \gamma T_i t + \delta t + v_{it}$
- Random effects:  $y_{it} = \alpha + \beta X_{it} + \gamma T_i t + \delta t + (u_i + v_{it})$
- $u_i$  is either a fixed effect specific to each individual (which now includes  $\theta T_i$ )
  - Each individual has a different intercept, but all individual have the same slopes
  - Error terms have constant variance and satisfy assumptions 2 and 3.
  - u<sub>i</sub> can be correlated with the other regressors without causing bias
- u<sub>i</sub> is a random effect, i.e. part of an individual-specific random component of the error term (error component model).
  - Intercepts and slopes are constant across individuals
  - However, in this case  $u_i$  cannot be correlated with  $X_{it}$  or  $T_i$ t if estimates of  $\beta$  and  $\gamma$  are to remain unbiased (this would violate assumption 2)
  - Disturbances do not have constant variance, but are randomly distributed across individuals

#### Fixed Effects Models

- In FEM, the intercept in the regression model is allowed to differ among individuals to reflect the unique feature of individual units.
  - This is done by using dummy variables, provided we take care of the dummy variable trap.
  - The FEM using dummy variables is known as the least-squares dummy variable model (LSDV).
- FEM is appropriate in situations where the individual-specific intercept may be correlated with one or more regressors, but consumes a lot of degrees of freedom when N (the number of cross-sectional units) is very large.



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# Random Effect Models

- The fixed effects model assumes that each group (firm) has a non-stochastic groupspecific component to y. Including dummy variables is a way of controlling for unobservable effects on y.
- But these unobservable effects may be stochastic (i.e. random). The Random Effects Model attempts to deal with this.
- In REM we assume that the intercept value of an individual unit is a random drawing from a much larger population with a constant mean.
- The individual intercept is then expressed as a deviation from the constant mean value.
- REM is more economical than FEM in terms of the number of parameters estimated.
- REM is appropriate in situations where the (random) intercept of each cross-sectional unit is uncorrelated with the regressors.
- Unlike in FEM, time-invariant regressors can be used in REM.

# Estimating Random Effects (RE) Models

- The RE model has the following composite errors  $w_{it} = u_i + v_{it}$ .
- Both components of the error term are assumed independent of the included variables

$$y_{it} = \alpha + \beta X_{it} + \gamma T_i t + \delta t + (u_i + v_{it})$$

- Because the model has two parts for the error, we obtain two variance estimates  $\sigma_{\!_{u}}{}^{2}$  and  $\sigma_{\!_{v}}{}^{2}$
- The variances differs across individuals, making the model heteroskedastic
- We therefore estimate the model using Generalized Least Squares (GLS) instead of OLS

#### Reminder for GLS



The measurement system used might be a source of variability, and the size of the measurement error is proportional to the measured quantity. In many cases, the variance is a function of the mean

Heteroskedasticity is known up to a Multiplicative Constant

• Example:

$$sav_{i} = \beta_{0} + \beta_{1}inc_{i} + u_{i}$$

$$Var(u_{i} | inc_{i}) = \sigma^{2}inc_{i}$$

$$h_{i} = inc_{i}$$

$$sav_{i} / \sqrt{inc_{i}} = \beta_{0}1 / \sqrt{inc_{i}} + \beta_{1}inc_{i} * 1 / \sqrt{inc_{i}} + k_{i}$$
• Transformed equation satisfies all G-M assumptions.

General Least Squares Estimator

- Estimating the transformed equation by OLS is called generalized least squares (GLS)...class of estimators
- GLS will be BLUE in this case
  - Provides more efficient estimates than if used OLS in untransformed analysis.
- Can uses s.e. for t-statistics, p-values, CI, and resulting R<sup>2</sup> is used for F-statistics

General Least Squares Estimator

- GLS estimator for correcting heteroskedasticity is called WLS estimator.
  - minimize the weighted sum of squared residuals (weighted by 1/h<sub>i</sub>), which is inverse of the variance.
  - Less weight is given to observations with a higher error variance; in contrast, OLS gives same weight to all observations because it is best when error variance is identical for all partitions of the population

General Least Squares Estimator

 $\Box$ WLS is great if we know what Var( $u_i / x_i$ ) looks like, but in most cases won't know form of heteroskedasticity. More typically, we don't know the form of the heteroskedasticity.

#### $\Box$ In this case, you need to estimate $h(\mathbf{x}_i)$

 $\Box$  Since we are *estimating* h( $x_i$ ) and using the estimate to transform the equation, call it feasible GLS.

□ Typically, we start with the assumption of a fairly flexible model, such as

 $\square \text{Var}(u/\boldsymbol{x}) = \sigma^2 \exp(\delta_0 + \delta_1 x_1 + \ldots + \delta_k x_k) \text{ , where } h(\boldsymbol{x}_i) = \exp(\delta_0 + \delta_1 x_1 + \ldots + \delta_k x_k)$ 

**\Box**Since we don't know the  $\delta$ , it be must estimated

General Least Squares Estimator

- Can transform above as
  - $u^2 = \sigma^2 \exp(\delta_0 + \delta_1 x_1 + \dots + \delta_k x_k) v$
  - v is error term
  - assume E(v/x) = 1 and E(v) = 1
- Taking natural logs of both sides:
  - $\ln(u^2) = \alpha_0 + \delta_1 x_1 + ... + \delta_k x_k + e... \alpha_0$  now contains original intercept and  $\log(\sigma^2)$
  - Assume E(e) = 0 and e is independent of x
- We don't have u, so replace with its estimate, û. Now can estimate this by OLS to get estimate of h(x<sub>i</sub>)

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# Testing the Fixed Effects Against the Pooled Cross Section model

 Since the FE model is simply an OLS model with individual dummies added, it can be tested against the pooled-cross section model using an F-test of the joint significance of the dummies

$$F(n-1, nT - n - k) = \frac{(e'e_{pooled} - e'e_{LSDV})/(n-1)}{(e'e_{LSDV})/(nT - n - k)} = \frac{(R_{LSDV}^2 - R_{pooled}^2)/(n-1)}{(1 - R_{LSDV}^2)/(nT - n - k)}$$

# Testing the Random Effects Against the Pooled Cross Section model

- Testing the RE model against the pooled cross-section model involves the Breusch-Pagan Lagrange Multiplier Test: this is essentially a  $\chi^2$  test with one degree of freedom that  $\sigma_u^2$ =0 and therefore the composite errors can be reduced to regular IID distributed errors
- To determine whether classical OLS (with only one constant term) should be used instead of a fixed or random effects specification, a Lagrange Multiplier test for correlation of error terms is used:  $H_0 : E[u_{it}u_{is}] = 0$

$$H_1: E\left[u_{it}u_{is}\right] \neq 0$$

- The test statistic has a Chi-squared distribution with one degree of freedom under the null hypothesis and is calculated as follows:  $LM = \frac{NT}{2(T-1)} \left[ \frac{\sum_{i=1}^{n} (T\tilde{\varepsilon}_{i})^{2}}{\sum_{i=1}^{n} (T\tilde{\varepsilon}_{i})^{2} \sum_{i=1}^{T} (e_{i})^{2}} - 1 \right]^{2}$
- If the test statistic exceeds the critical value, OLS should not be used.

# Testing FE vs. RE effects

- The null hypothesis of the test is that the individual unobserved effects (the fixed effects and the random effects) are uncorrelated with the included variables  $X_{it}$ 
  - If that hypothesis is rejected, FE is the preferred model because it is consistent and RE is not
  - It that null hypothesis is not rejected both models are consistent, but RE is more *efficient* and is therefore preferred
- The test compares the coefficient estimates from both models and if they are jointly not significantly different from each other, i.e., there is no detectable bias in RE (Null hypothesis is accepted and RE is preferred.

A test that does that is the **Hausman test** 

$$LM = (b_{LSDV} - b_{random}) \hat{W}^{-1} (b_{LSDV} - b_{random}) \sim \chi^2(k),$$

• Where

$$\hat{W} = Var[b_{LSDV} - b_{random}] = Var(b_{LSDV}) - Var(b_{random})$$

## Fixed or Random Effects?

- For random effects:
  - Random effects are efficient
  - Why should we assume one set of unobservables fixed and the other random?
  - Sample information more common than that from the entire population?
  - Can deal with regressors that are fixed across individuals
- Against random effects:
  - Likely to be correlation between the unobserved effects and the explanatory variables. These are assumed to be zero in the random effects model, but in many cases we might expect them to be non-zero.
  - This implies inconsistency due to omitted-variables in the RE model.
  - In this situation, fixed effects is inefficient, but still consistent.

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Source: Oscar Torres-Reyna





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Run a fixed effects model and save the estimates, then run a random model and save the estimates, then perform the test. See below.

xtreg y x1, fe
estimates store fixed
xtreg y x1, re
estimates store random
hausman fixed random

. hausman fixed random

x1	2.48e+09	1.25e+09	1.23e+09	6.41e+08
	(b)	(B)	(b-B)	sqrt(diag(V_b-V_B))
	fixed	random	Difference	S.E.

b = consistent under Ho and Ha; obtained from xtreg
B = inconsistent under Ha, efficient under Ho; obtained from xtreg

Test: Ho: difference in coefficients not systematic

$$chi2(1) = (b-B)'[(V_b-V_B)\wedge(-1)](b-B)$$

$$= 3.67$$

$$Prob>chi2 = 0.0553 \blacktriangleleft \qquad \text{If this is < 0.05 (i.e. significant) use fixed effects.}$$

### References

- Wooldridge Intro, Chapter 14.
- Wooldridge Panel, Chapter 10.
- Oscar Torres-Reyna, Panel Data Analysis Fixed & Random Effects (using Stata 10)
- Slides of Ragui Assaad and Caroline Krafft.

Thank you for your attention